

WHERE $\phi(x) = (x_1^2, \sqrt{2}x_1x_2, x_2^2)^T$ FEATURE SPACE

IF $k_1(x, x')$ KERNEL, THEN
 $k_2(x, x')$

$ck_1(x, x')$
 $f(x)k_1(x, x')f(x')$
 $\exp(k_1(x, x'))$
 $k_1(x, x')k_2(x, x')$
 ...

$$\text{DIM}(x) \leftrightarrow \text{DIM}(\phi(x))$$

ETC. (PAGE 236)!

$$k(\|x - x'\|) = \phi^T(x) \phi(x')$$

(RADIAL BASIS FUNCTIONS) \hookrightarrow ∞ -DIM FEATURE SPACE

$$k(x, x') = \exp(-\|x - x'\|^2 / 2\sigma^2)$$

$$\begin{aligned} k(x, x') &= (x^T x' + c)^2 \rightarrow \phi(x) = (\sqrt{c}, \sqrt{2c}x_1, \sqrt{2c}x_2, \sqrt{2}x_1x_2, \\ &= (x^T x' + c)^M \rightarrow \phi(x) = \dots \quad x_1^2, x_2^2) \\ &\quad \text{ALL TERMS UP TO DEGREE } M \end{aligned}$$

RADIAL BASIS FUNCTION NETWORKS (CH. 6.3)

$$\phi_j(x) = h(\|x - \mu_j\|)$$

$$\{x_n, t_n\} \quad y(x, w) = f(x) = \sum_{n=1}^N w_n h(\|x - x_n\|)$$

\hookrightarrow LS OPTIMUM

NOISE ON $x = v(\xi)$

$$E = \frac{1}{2} \sum_{n=1}^N \int \{y(x_n + \xi) - t_n\}^2 v(\xi) d\xi$$

$$y(x_n) = \sum_{n=1}^N t_n h(x - x_n)$$

$$\sum_n h(x - x_n) = 1$$

NORMALIZATION

(FIG. 6.3)

$$\frac{v(x - x_n)}{\sum_{n=1}^N v(x - x_n)}$$